

## Differential Geometry of Framed Curves

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SESSION 7: SOLUTIONS

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**Solution 1** Both factors change sign in the numerator while the denominator is left unchanged.

**Solution 2**

- Under a translation  $\mathbf{x} \mapsto \mathbf{x} + \mathbf{a}$  for some  $\mathbf{a} \in \mathbb{R}^3$ :

$$(\mathbf{x}(\sigma) + \mathbf{a}) - (\mathbf{x}(s) + \mathbf{a}) = \mathbf{x}(\sigma) - \mathbf{x}(s)$$

$$(\mathbf{x}(\sigma) + \mathbf{a})' \wedge (\mathbf{x}(s) + \mathbf{a})' = \mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)$$

- Under a rotation  $\mathbf{x} \mapsto R\mathbf{x}$  for some  $R \in \text{SO}(3)$ :

$$R\mathbf{x}(\sigma) - R\mathbf{x}(s) = R(\mathbf{x}(\sigma) - \mathbf{x}(s)).$$

$$\begin{aligned} (R\mathbf{x}(\sigma))' \wedge (R\mathbf{x}(s))' &= (R\mathbf{x}'(\sigma))^\times (R\mathbf{x}'(s)) \\ &= |R|R^{-T}(\mathbf{x}'(\sigma))^\times R^{-1}(\mathbf{x}'(s)) \\ &= R(\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)). \end{aligned} \tag{1}$$

Accordingly, under rigid rotation, the denominator is left unchanged while the numerator becomes

$$\begin{aligned} (R\mathbf{x}(\sigma) - R\mathbf{x}(s)) \cdot (R\mathbf{x}(\sigma))' \wedge (R\mathbf{x}(s))' &= \left[ R(\mathbf{x}(\sigma) - \mathbf{x}(s)) \right] \cdot \left[ R(\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)) \right], \\ &= (\mathbf{x}(\sigma) - \mathbf{x}(s)) \cdot R^T R(\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)), \\ &= (\mathbf{x}(\sigma) - \mathbf{x}(s)) \cdot (\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)). \end{aligned} \tag{2}$$

- Under a dilation  $\mathbf{x} \mapsto \lambda\mathbf{x}$ , we get the factor  $\lambda^3$  both in the nominator and the denominator, so  $\text{Wr}$  is invariant under dilations as well.

Note that if  $R \in O(3) \setminus \text{SO}(3)$ , then  $|R| = -1$  and a minus sign would appear in (1). Accordingly, the Writhe flips sign under isometries of determinant -1.

**Solution 3** For a planar curve, the three vectors  $(\mathbf{x}(\sigma) - \mathbf{x}(s))$ ,  $\mathbf{x}'(\sigma)$  and  $\mathbf{x}'(s)$  are coplanar. Their scalar triple product vanishes and  $I_{\text{Wr}} = 0$ .

We can obtain the same result making use of question 2 by noticing that the curve is left unchanged by reflexion through its plane (an isometry of determinant  $-1$ ) while the Writhe must change sign.

**Solution 4** Given  $\mathbf{e} \cdot (\mathbf{e}_s \wedge \mathbf{e}_\sigma) = 0$ , we have

$$(\mathbf{x}(s) - \mathbf{x}(\sigma)) \cdot (\mathbf{x}'(s) \wedge \mathbf{x}'(\sigma)) = 0,$$

which is equivalent to

$$\mathbf{x}'(s) \cdot [\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))] = 0 \tag{3}$$

Differentiate (3) with respect to  $s$  to get

$$\mathbf{x}''(s) \cdot [\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))] = 0. \tag{4}$$

But  $\mathbf{x}' = v\mathbf{t}$  with  $v = \|\mathbf{x}'\| = \frac{dS}{ds}$  where  $S$  is the arc-length along  $\mathbf{x}$ , so we have

$$\mathbf{x}'' = v'\mathbf{t} + v\mathbf{t}' = v'\mathbf{t} + v^2\kappa\mathbf{n}. \quad (5)$$

Eqs. (3-5) imply that  $\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))$  is perpendicular to the  $(\mathbf{t}, \mathbf{n})$ -plane so it must be along  $\mathbf{b}(s)$ :

$$\mathbf{b}(s) = \pm \frac{\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))}{\|\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))\|}. \quad (6)$$

Differentiate (6) with respect to  $s$  to get

$$\mathbf{b}'(s) = \pm \frac{\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)}{\|\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))\|} - \mathbf{w},$$

where  $\mathbf{w}$  is parallel to  $\mathbf{b}$ .

Finally  $\frac{d\mathbf{b}}{ds} = \frac{d\mathbf{b}}{dS} \frac{dS}{ds} = -v\tau\mathbf{n}$  so that

$$\begin{aligned} -v\kappa\tau = \mathbf{b}'(s) \cdot \kappa\mathbf{n}(s) &= \mathbf{b}'(s) \cdot \frac{\mathbf{x}''(s) - \frac{v'(s)}{v(s)}\mathbf{x}'(s)}{v^2} \\ &= \frac{\mathbf{x}'(\sigma) \wedge \mathbf{x}'(s)}{\|\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))\|} \cdot \frac{\mathbf{x}''(s)}{v^2} \\ &= \frac{(\mathbf{x}'(s) \wedge \mathbf{x}''(s)) \cdot \mathbf{x}'(\sigma)}{\|\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))\|v^2}. \end{aligned}$$

But  $(\mathbf{x}'(s) \wedge \mathbf{x}''(s))$  is perpendicular to both  $\mathbf{t}$  and  $\mathbf{n}$  and so it must be parallel to  $\mathbf{x}'(\sigma) \wedge (\mathbf{x}(s) - \mathbf{x}(\sigma))$  and so it is perpendicular to  $\mathbf{x}'(\sigma)$ . Hence the torsion vanishes identically. The curve is planar.

### Solution 5

**Step 1:** Consider the planar problem of finding a circle through two points  $A$  and  $X$  and tangent to a unit vector  $\mathbf{t}$  at  $B$ . Let  $\ell$  be the straight line through  $A$  and  $B$ ,  $\theta$  be the angle between  $\ell$  and the line  $q$  subtended by  $\mathbf{t}$ ,  $a$  be the distance between  $A$  and  $B$ ,  $O$  the centre of the circle,  $p$  the perpendicular to  $AB$  through  $O$ , and  $P$  and  $Q$  the respective intersections of  $p$  with  $AB$  and  $q$ . The angle  $AOP$  has amplitude  $\theta$  since the triangles  $POA$  and  $AQO$  are similar. Then in the right-angled triangle  $\theta$ , we find

$$\sin \theta = \frac{a}{2R}, \quad (7)$$

where  $R$  is the radius of the circle.

**Step 2:** Modify the expression for writhe. We have already showed (technically, we did it for  $Lk$  but the proof is identical for  $Wr$ ) that

$$Wr = \frac{1}{4\pi} \int \int \mathbf{e} \cdot (\mathbf{e}_s \times \mathbf{e}_\sigma) ds d\sigma, \quad (8)$$

where  $e(s, \sigma) = \frac{\mathbf{x}(\sigma) - \mathbf{x}(s)}{\|\mathbf{x}(\sigma) - \mathbf{x}(s)\|}$ . Then consider the fact that on the one hand

$$(\mathbf{e} \times \mathbf{e}_s) \times (\mathbf{e} \times \mathbf{e}_\sigma) = \left( \mathbf{e} \cdot (\mathbf{e}_s \times \mathbf{e}_\sigma) \right) \mathbf{e}, \quad (9)$$

and on the other hand, the fact that

$$\mathbf{e} \times \mathbf{e}_\sigma = \mathbf{e} \times \frac{\mathbf{x}'(\sigma)}{a(s, \sigma)} = \frac{\sin \theta_1}{a(s, \sigma)} \mathbf{n}_1 \stackrel{(7)}{=} \frac{\mathbf{n}_1}{d(s, \sigma)}, \quad \text{and} \quad \mathbf{e} \times \mathbf{e}_s = \frac{\mathbf{n}_2}{d(\sigma, s)}. \quad (10)$$

where  $\theta_1$  (resp.  $\theta_2$ ) is the angle between the straight lines subtended by  $\mathbf{e}$  and by  $\mathbf{e}_\sigma$  (resp.  $\mathbf{e}_s$ ),  $a(s, \sigma) = \|\mathbf{x}(\sigma) - \mathbf{x}(s)\|$ , and  $\mathbf{n}_1$  (resp.  $\mathbf{n}_2$ ) is the unit vector along  $\mathbf{e} \times \mathbf{e}_\sigma$  (resp.  $\mathbf{e} \times \mathbf{e}_s$ ). Substituting (10) in (9) gives the result.

**Solution 6**

- $\mathbf{x}(s) = (r \cos s, r \sin s, rps), \quad \mathbf{x}'(s) = (-r \sin s, r \cos s, rp).$
- $\mathbf{r}(s, \sigma) := \mathbf{x}(s) - \mathbf{x}(\sigma) = r(\cos s - \cos \sigma, \sin s - \sin \sigma, p(s - \sigma)).$
- $\|\mathbf{r}\| = r\sqrt{4 \sin^2 \left(\frac{s-\sigma}{2}\right) + p^2(s - \sigma)^2}.$

$$\begin{aligned} \mathbf{r} \cdot (\mathbf{r}_\sigma \wedge \mathbf{r}_s) &= r^3 \begin{vmatrix} \cos s - \cos \sigma & \sin s - \sin \sigma & p(s - \sigma) \\ -\sin s & \cos s & p \\ -\sin \sigma & \cos \sigma & p \end{vmatrix} \\ &= r^3 p \left[ 4 \sin^2 \left( \frac{s - \sigma}{2} \right) - (s - \sigma) \sin(s - \sigma) \right]. \end{aligned}$$

$$\begin{aligned} I_{\text{Wr}} &= \frac{\mathbf{r} \cdot (\mathbf{r}_\sigma \wedge \mathbf{r}_s)}{\|\mathbf{r}\|^3} \\ &= \frac{p}{2} \cdot \frac{\sin^2 \left( \frac{s-\sigma}{2} \right) - \frac{s-\sigma}{2} \sin \left( \frac{s-\sigma}{2} \right) \cos \left( \frac{s-\sigma}{2} \right)}{\left[ \sin^2 \left( \frac{s-\sigma}{2} \right) + p^2 \left( \frac{s-\sigma}{2} \right)^2 \right]^{\frac{3}{2}}}. \end{aligned}$$

As indicated in the hint we compute

$$\left( \frac{w}{\sqrt{\sin^2 w + p^2 w^2}} \right)' = \frac{\sin^2 w - w \sin w \cos w}{(\sin^2 w + p^2 w^2)^{\frac{3}{2}}}. \quad (11)$$

Finally, compute

$$\begin{aligned} \text{Wr}(\mathbf{x}) &= \frac{1}{4\pi} \int_0^L d\sigma \int_0^L I_{\text{Wr}}(s, \sigma) ds \\ &= \frac{1}{4\pi} \int_0^L d\sigma \int_{-\frac{\sigma}{2}}^{\frac{L-\sigma}{2}} \frac{p}{2} \frac{\sin^2 t - t \sin t \cos t}{(\sin^2 t + p^2 t^2)^{\frac{3}{2}}} 2 dt \quad \text{where } t = \frac{s - \sigma}{2} \\ &= \frac{p}{4\pi} \lim_{\varepsilon \rightarrow 0^+} \left\{ \int_0^L d\sigma \left[ \int_{-\frac{\sigma}{2}}^{-\varepsilon} \frac{\sin^2 t - t \sin t \cos t}{(\sin^2 t + p^2 t^2)^{\frac{3}{2}}} dt + \int_{\varepsilon}^{\frac{L-\sigma}{2}} \frac{\sin^2 t - t \sin t \cos t}{(\sin^2 t + p^2 t^2)^{\frac{3}{2}}} dt \right] \right\} \\ \stackrel{(11)}{=} & \frac{p}{4\pi} \int_0^L d\sigma \lim_{\varepsilon \rightarrow 0^+} \left\{ \left[ \frac{t}{\sqrt{\sin^2 t + p^2 t^2}} \right]_{-\frac{\sigma}{2}}^{-\varepsilon} + \left[ \frac{t}{\sqrt{\sin^2 t + p^2 t^2}} \right]_{\varepsilon}^{\frac{L-\sigma}{2}} \right\}, \quad (12) \end{aligned}$$

$$\begin{aligned} &= \frac{p}{4\pi} \left[ \int_0^L \frac{(L - \sigma)/2}{\sqrt{\sin^2(L - \sigma)/2 + p^2(L - \sigma)^2/4}} d\sigma + \int_0^L \frac{\sigma/2}{\sqrt{\sin^2 \sigma/2 + p^2 \sigma^2/4}} d\sigma \right] \\ &\quad - \frac{pL}{2\pi} \lim_{\varepsilon \rightarrow 0} \frac{\varepsilon}{\sqrt{\sin^2 \varepsilon + p^2 \varepsilon^2}}, \\ &= \frac{p}{4\pi} \left[ \int_{L/2}^0 \frac{-2u du/2}{\sqrt{\sin^2 u + p^2 u^2}} + \int_0^{L/2} \frac{2v dv}{\sqrt{\sin^2 v + p^2 v^2}} - \frac{2L}{\sqrt{1 + p^2}} \right], \\ &\quad \text{with } u = \frac{L - \sigma}{2} \text{ and } v = \frac{\sigma}{2}, \end{aligned}$$

$$= \frac{p}{\pi} \int_0^{\frac{L}{2}} \frac{v dv}{\sqrt{\sin^2 v + p^2 v^2}} - \frac{pL}{2\pi} \frac{1}{\sqrt{1 + p^2}}. \quad (13)$$

To study the asymptotic behaviour, we first take a derivative w.r.t.  $L$  which yields

$$\frac{d\text{Wr}}{dL} = \frac{p}{2\pi} \left( \frac{L}{\sqrt{\sin^2 L + p^2 L^2}} - \frac{1}{\sqrt{1 + p^2}} \right), \quad (14)$$

$$= \frac{p}{2\pi} \left( \frac{1}{\sqrt{\frac{1}{L^2} \sin^2 L + p^2}} - \frac{1}{\sqrt{1 + p^2}} \right) \xrightarrow{L \rightarrow \infty} \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} \right). \quad (15)$$

Hence for large  $L$ , we have the following asymptotic behaviour for  $\text{Wr}$ :

$$\text{Wr}(L) \stackrel{L \rightarrow \infty}{\sim} \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} \right) L. \quad (16)$$

This asymptotic result can also be derived somewhat more rigorously by the following analysis: change variables according to  $g = 1/L$  so that  $L \rightarrow \infty$  becomes  $g \rightarrow 0^+$ . The differential equation (14) becomes singular:

$$-g^2 \frac{d\text{Wr}}{dg} = \frac{p}{2\pi} \left( \frac{1}{\sqrt{g^2 \sin^2 1/g + p^2}} - \frac{1}{\sqrt{1 + p^2}} \right). \quad (17)$$

We want to study the differential equation (17) as  $g \rightarrow 0$ . First note that  $|p| \leq \sqrt{g^2 \sin^2 1/g + p^2} \leq \sqrt{g^2 + p^2}$ . Accordingly

$$\frac{1}{|p|} \geq \frac{1}{\sqrt{g^2 \sin^2 1/g + p^2}} \geq \frac{1}{\sqrt{g^2 + p^2}} = \frac{1}{|p|} - \frac{g^2}{2|p|^3} + O(g^4), \quad (18)$$

so that

$$\frac{1}{\sqrt{g^2 \sin^2 1/g + p^2}} = \frac{1}{|p|} + O(g^2). \quad (19)$$

Next we expand  $\text{Wr}(g)$  close to  $g = 0$  as

$$\text{Wr}(g) = w_{-1} g^{-1} + w_0 + w_1 g + O(g^2) \Rightarrow \text{Wr}'(g) = -\frac{w_{-1}}{g^2} + w_1 + O(g), \quad (20)$$

where  $w_{-1}$ ,  $w_0$  and  $w_1$  are constant coefficients that we will try to find.

Substituting (19) and (20) in (17) yields

$$-w_{-1} + w_1 g^2 + O(g^3) = \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} + O(g^2) \right). \quad (21)$$

Hence we find  $w_{-1} = \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} \right)$  but note that this analysis does not prescribe  $w_0$  or  $w_1$ .

Substituting our result and  $g = L^{-1}$  in (20) gives

$$\text{Wr}(L) = \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} \right) L + w_0 + w_1 \frac{1}{L} + O\left(\frac{1}{L^2}\right) \stackrel{L \rightarrow \infty}{\sim} \frac{p}{2\pi} \left( \frac{1}{|p|} - \frac{1}{\sqrt{1 + p^2}} \right) L. \quad (22)$$

We see that we have gathered a little more information as to the behaviour of the solutions at higher order in  $1/L$ . To find  $w_0$ , we could write an expansion close to  $L = 0$  and then enforce that both expansions must match smoothly at say  $L = 1$ . That sort of argument is useful to obtain approximate solutions to many non-linear problems and is well worth keeping in mind.