

## Serie 3

**Exercise 1** *The forward and backward errors can be quite different. Consider the linear system  $Ax = b$ , with:*

$$A = \begin{pmatrix} 99 & 98 \\ 100 & 99 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 1 \end{pmatrix},$$

*the exact solution of which is*

$$x = \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

*Let  $\hat{x}_1$  be the solution computed with Matlab and assume that two different numerical methods yield the following results:*

$$\hat{x}_2 = \begin{pmatrix} 2.97 \\ -2.99 \end{pmatrix}, \quad \hat{x}_3 = \begin{pmatrix} 1.01 \\ -0.99 \end{pmatrix}.$$

1. *In Matlab, compute the matrix condition number and for each approximation the error and the residuum.*
2. *For a given approximation  $\hat{x}$ , let be a matrix  $E$  such that*

$$E\hat{x} = r = b - A\hat{x}. \tag{1}$$

*Then, the approximation is obtained as the exact solution of the problem*

$$(A + E)\hat{x} = b. \tag{2}$$

*A solution of (1) is given by*

$$\bar{E} = \frac{r\hat{x}^t}{\hat{x}^t\hat{x}}. \tag{3}$$

*Use (1) and (3) for proving that, in the euclidean norm, one has:*

$$\|\bar{E}\|_2 = \frac{\|r\|_2}{\|\hat{x}\|_2} = \min_{E\hat{x}=r} \|E\|_2;$$

*hence the norm of  $\bar{E}$  yield an a posteriori measure of the backward error. Compute these matrices and their norm in Matlab for the three approximations.*

3. *With the help of (1) and (3), show that the relative forward error is bounded like:*

$$\frac{\|x - \hat{x}\|_2}{\|\hat{x}\|_2} \leq \kappa(A) \frac{\|\bar{E}\|_2}{\|A\|_2}, \quad \kappa(A) = \|A\|_2 \|A^{-1}\|_2;$$

*in Matlab, compute this bound for the three approximations and compare with the computed values of the error.*

**Exercise 2** *Let be a vector  $x \in \mathbb{R}^n$  and a matrix  $A \in \mathcal{L}(\mathbb{R}^n)$ . The maximum (or  $l_\infty$ ) and  $l_1$  norms in  $\mathbb{R}^n$  are defined by*

$$\|x\|_\infty = \max_{1 \leq i \leq n} |x_i|, \quad \|x\|_1 = \sum_{i=1}^n |x_i|.$$

*Using the definition of the norm of  $\mathcal{L}(\mathbb{R}^n)$  induced by the norm of  $\mathbb{R}^n$ :*

$$\|A\| = \max_{\|x\|=1} \|Ax\|,$$

*prove that:*

1.

$$\|A\|_{\infty} = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|,$$

2.

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|,$$

3.

$$\|A^t\|_{\infty} = \|A\|_1.$$

**Exercise 3** Estimate in Matlab the normwise backward and forward errors for both linear systems: 1) with a random matrix of order  $n = 100$  and 2) with the ill-conditioned matrix of order  $n = 20$  in the file `A.mat`. In both cases, the exact solution shall be given by  $x(i) = \sqrt{i}$  and the function `rcond` shall be used for estimating the inverse of the condition number. Compare the estimates to the "exact" backward and forward errors.

**Exercise 4** Given  $f \in C[0, 1]$ , one consider the problem of finding a function  $u \in C^2[0, 1]$  such that:

$$\begin{aligned} -u''(t) &= f(t), \quad 0 < t < 1, \\ u(0) &= u(1) = 0. \end{aligned}$$

With the help of the regular partition

$$t_i = ih, \quad i=0,1,2,\dots,n+1, \quad h = 1/(n+1),$$

of  $[0, 1]$ , one looks for a finite differences approximation of  $u$ ,  $u_i \simeq u(x_i)$ , defined by the scheme

$$u''(t_i) \simeq -\frac{u_{i+1} + u_{i-1} - 2u_i}{h^2} = f(t_i), \quad i=1,2,\dots,n. \quad (4)$$

1. Write the linear system (4) in matrix form  $Ax = b$ .

2. With Matlab, for  $f(x) = \sin(\pi x)$ ,  $n = 24$ , compute the componentwise backward error

$$\omega_{\infty} = \max_i \frac{|r_i|}{(|A| |\hat{x}| + |b|)_i},$$

and estimate the forward error with the bound

$$\frac{\|\hat{x} - x\|_{\infty}}{\|x\|_{\infty}} \leq 2\kappa_{\infty}(A)\omega_{\infty}.$$

Compare to the "exact solution" and discuss the results.