Computations with the cgDNA+ coarse-grain model of DNA

Federica PADOVANO

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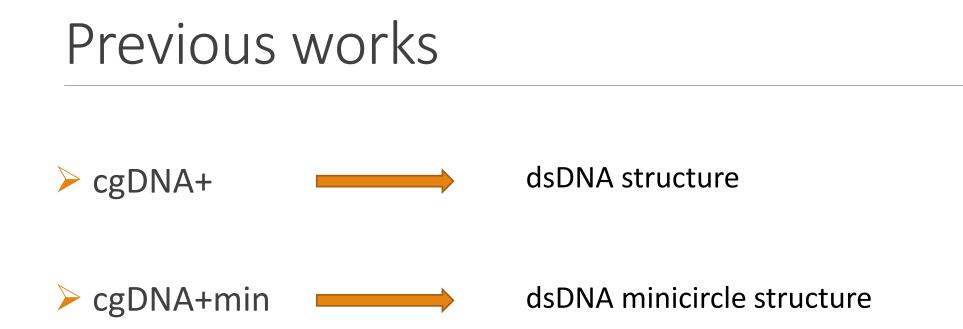
Goal of the semester project

bBDNA software:



- significant computational cost
- hecessary for the initial guess

Find a **procedure to find a good initial guess** for the energy minimization without using bBDNA software



cgDNA+

- Rigid base model: each base is represented by a frame in SE(3).
- Gaussian pdf:

$$\rho(w; S, \mathcal{P}) = \frac{1}{Z} e^{-\beta U(w; S, \mathcal{P})},$$

$$U(w; S, \mathcal{P}) = \frac{1}{2} (w - \mu(S, \mathcal{P}))^T K(S, \mathcal{P}) (w - \mu(S, \mathcal{P})).$$

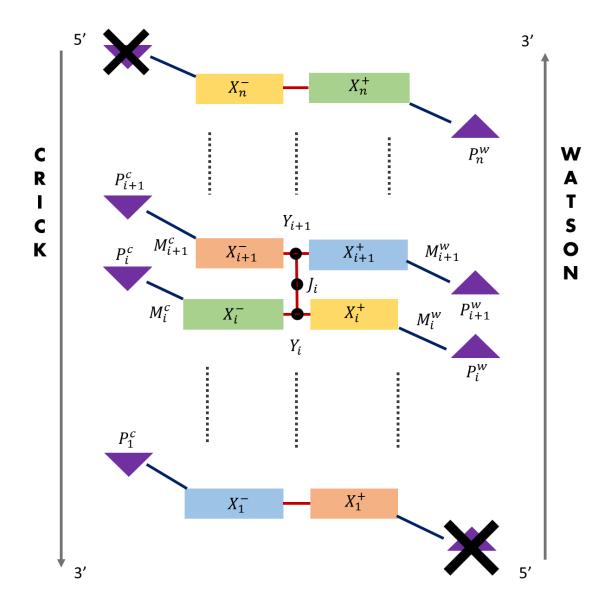
Coordinates:

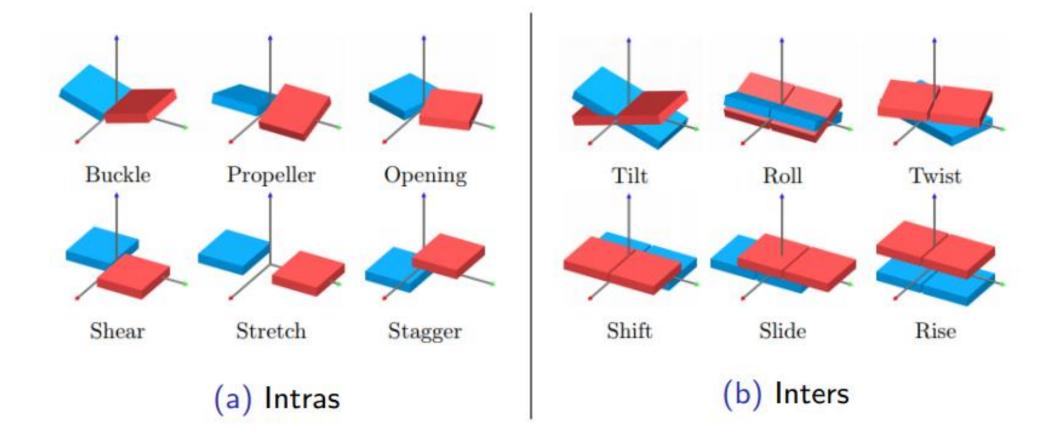
$$w = (x_1, x_1^c, y_1, x_2^w, x_2, x_2^c, y_2, ..., x_i^w, x_i, x_i^c, y_i, ..., y_{n-1}, x_n^w, x_n) \in \mathbb{R}^{24n-18}$$

where $x_i, x_i^c, x_i^w, y_i \in \mathbb{R}^6$,

cgDNA+

- **Rigid bodies**
- Relative coordinates w.r.t. a midway frame
- Cayley vector + Translation vector
- Base + Base pair + Phosphate



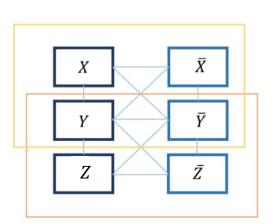


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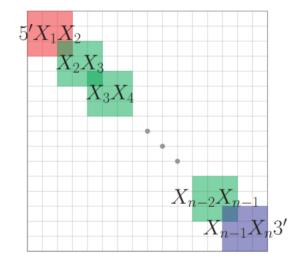
Three assumptions made on the energy:

- has a shifted quadratic form
- the total energy is a sum over level junctions energies

The coefficient in the local junction energy depends on the local dimer sequence step



(a) Interactions among the neighbours.



(b) Stiffness matrix construction.

cgDNA+ Periodicity

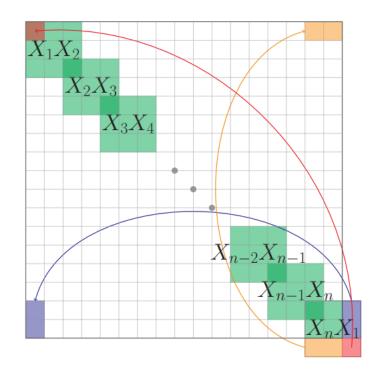
1 2 N

 $X_1 \dots X_n X_1 \dots X_n \dots \dots X_1 \dots X_n$

↓ BASE SEQUENCE

- Extra set of inter coordinates: inter between base pairs n and 1
- Extra block split in four corners: interactions between bases n and 1

STIFFNESS MATRIX



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- Uses quaternions
 - $\bullet \ 1$ quaternion & 1 vector in \mathbb{R}^3 for each base pair
 - Benefits: simple expression for the closure assumption
 - Cost: extra transformation to recover inters
- New coordinate vector

•
$$z = (x_1, o_1, q_1, x_2, o_2, q_2, \dots, x_{n-1}, o_{n-1}, q_{n-1}, x_n)$$

Locally recover original cgDNA inter coordinates:

$$y_i := f(o_i, q_i, o_{i+1}, q_{i+1}) = (\theta_i^1, \theta_i^2, \theta_i^3, \zeta_i^1, \zeta_i^2, \zeta_i^3), \ heta_i^a = rac{10q_{i+1}^T B_a q_i}{q_{i+1}^T q_i}, \ a = 1, 2, 3, \quad \zeta_i^T = (o_{i+1} - o_i) R(q_{i+1} + q_i).$$

R(q) is the rotation matrix induced by q and B_a are matrices used to form an orthonormal base for the quaternions.

• global transformation w = F(z), Energy $U(z) = \frac{1}{2}(F(z) - \mu)^T K(F(z) - \mu)$

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- Construct periodic stiffness matrix and periodic ground-state (parameter set)
- Run bBDNA software to obtain a continuum initial guess
- Discretize the initial guess
- Run the energy minimization starting in the initial guess:
 - Assumptions for the continuum model are slightly different than the ones of the discrete case
 - During the discretization process, errors are induced.
- Convert quaternions into inter variables

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Assumptions on energy and quaternions:

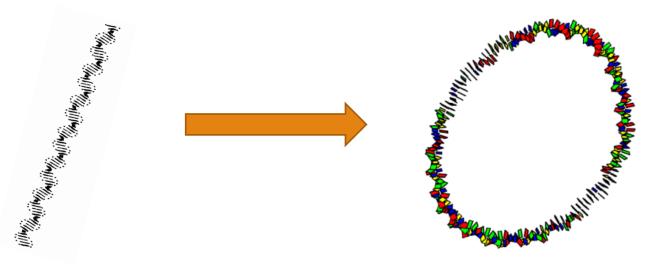
- has a shifted quadratic form
- the total energy is a sum over level junctions energies
- The coefficient in the local junction energy depends on the local dimer sequence step
- \succ Contraint: $||q_i||^2 = 1 \quad \forall i = 1 \dots, n$

$$\mathcal{L}(z) = \frac{1}{2} (F(z) - \mu)^T K(F(z) - \mu) + \lambda \sum_{i=1}^n (||q_i||^2 - 1)^2$$

Construct an initial guess

Two main steps:

- > generate special helicoidal configuration that have specific integer link number m
- b deform the helicoidal equilibrium into a twisted circle



$$w = (x_1, u, v, x_2, u, v, \dots, x_n, u, v) \in \mathbb{R}^{24n}$$

 \succ the vectors $u, v \in \mathbb{R}^3$ (*inter* variables) are always the same

- > uniformity of *inter* variables
- \succ rotation axis (u) is parallel to the helix axis
- \geq each base pair frame origin has the same distance (ho) from the axis center-line
- > relative distance between two consecutive base pairs is the same

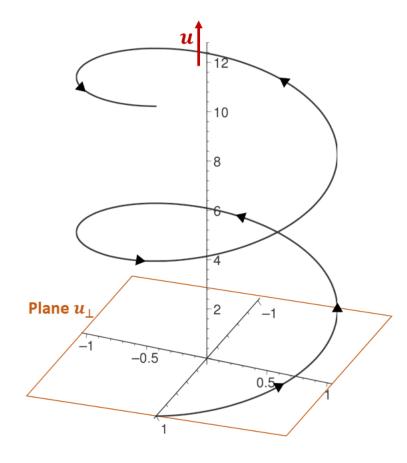
base pairs frame axis rotate through u

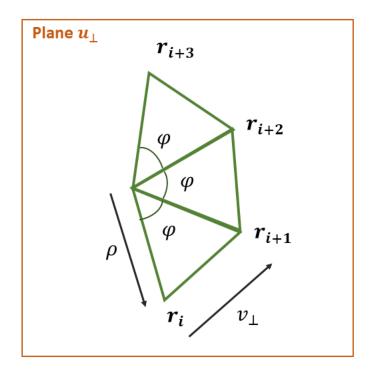
 v_{\perp} = translation in the plane u_{\perp}

 $\boldsymbol{v}_{\parallel}$ = translation along direction \boldsymbol{u}

 ϕ = angle of rotation

$$\rho = \frac{1}{2} \frac{v_{\perp}}{\sin(\varphi/2)}$$





$$z = (x_1, x_2, ..., x_n, u, v) \in \mathbb{R}^{18n+6}$$

 $Pz = w$

$$P = \begin{bmatrix} I_{18} & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & I_6 \\ 0 & I_{18} & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & I_6 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & I_{18} & 0 \\ 0 & 0 & \dots & 0 & I_6 \end{bmatrix} \in \mathbb{R}^{24n \times 18n + 6}$$

ENERGY:

-
$$U^*(z) = \frac{1}{2}(Pz - \mu)^\top K(Pz - \mu)$$

$$\nabla U^*(z) = 0 \iff P^\top K P z = P K \mu$$

Solve this equation to find the global minimum

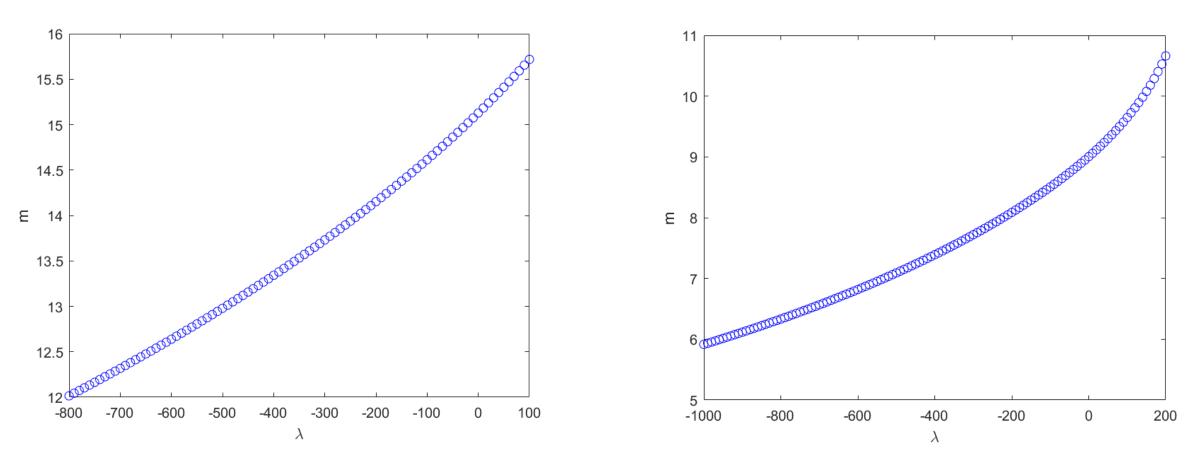
the number of links between the two ends must be an integer number m

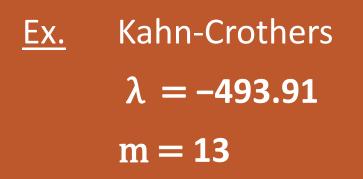
 $\varphi n = 2\pi m$ $\|u\| = 10 \tan \frac{\varphi^*}{10}$ $\|u\| = 10 \tan \frac{\pi m}{n}$

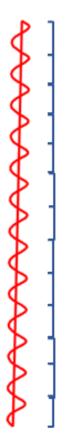
$$z^{T}Ez = ||u||^{2} \qquad E = \begin{bmatrix} 0 & \dots & 0 & 0 \\ 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & I_{3} & 0 \\ 0 & \dots & 0 & 0 \end{bmatrix} \in \mathbb{R}^{18n+6\times18n+6}$$
$$\mathcal{L}(z;\lambda) = U^{*}(z) + \lambda h(z)$$
$$\nabla \mathcal{L}(z,\lambda) = 0 \iff (P^{T}KP - \lambda E)z = PK\mu$$
$$\square$$
Solve this equation to find the minimum

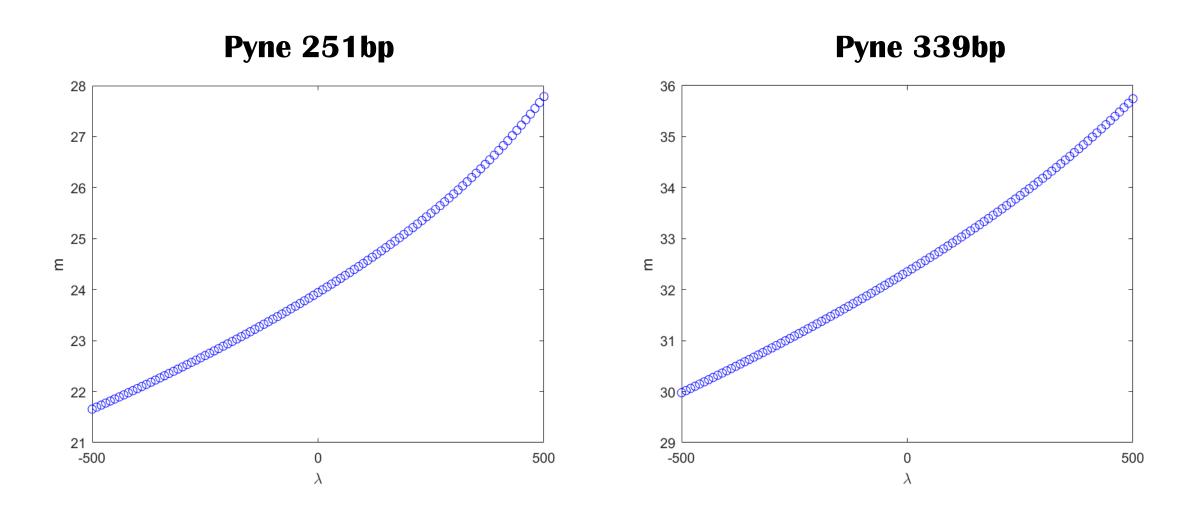
Kahn-Crothers

Widom 601



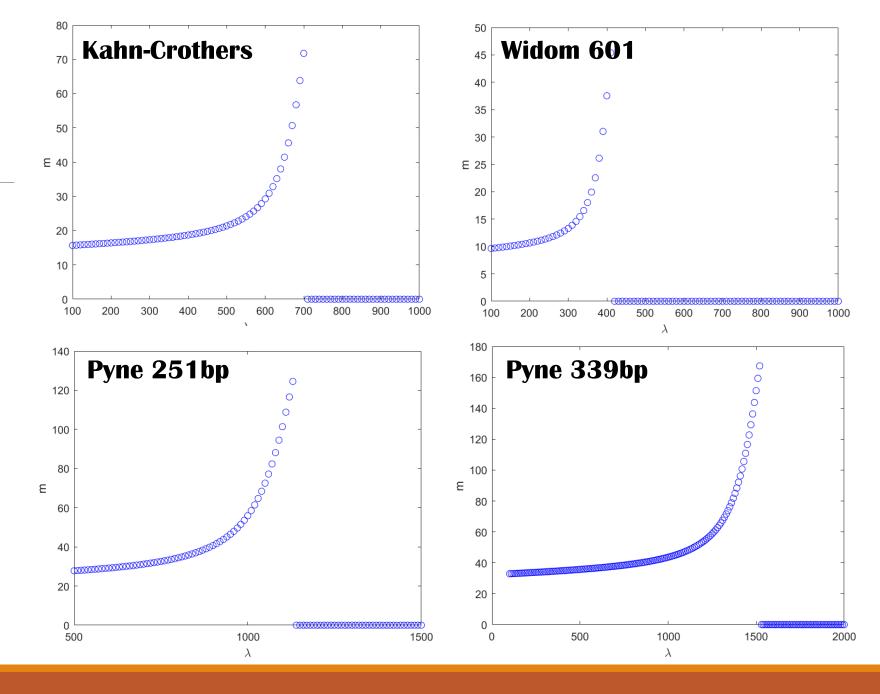






In general we should check that the **matrix** is **symmetric** and **positive definite**

$$(P^T K P - \lambda E)z = P K \mu$$



Analysis on initial guesses

If we **change inter variables of the periodic ground-state**, while intras and phosphate are left as they are, we can find a good initial guess for the energy optimization

Consider two different initial guesses for the energy optimization:

>configuration obtained with the bBDNA software

configuration in which the intra and phosphate coordinates are the same of the periodic ground-state, while the inter coordinates are the ones of the configuration obtained with the bBDNA software

Analysis on initial guesses

Sequences:

- ≻Kahn-Crothers
- > Widom 601
- Pyne 251bp
- Pyne 339bp

MatLab fminunc:

- Trust Region
- > Quasi-Newton

Results

Kahn-Crothers (4 i.g.): they all converge to the same solution, and they are all local minima

Pyne 251 (4 i.g.): they all converge to the same solution, and they are all local minima

Abs. difference: **1.0e-3** Negative eigenvalues: **0**

Abs. difference: **1.0e-2** Negative eigenvalues: **0**

Results

- > Widom 601 (4 i.g.):
 - GUESS 1: absolute difference 1.0e-3, but one has a negative eigenvalue (-1.3285e-05) and the other one has all positive eigenvalues (minimum is 3.4011e-05)
 - GUESS 2: converge to the same point which is not a minimum (Quasi-Newton + Trust Region)
 - GUESS 3: converge to the same saddle point
 - GUESS 4: they all converge to the same solution, and they are all local minima (*Quasi-Newton* + *Trust Region*)

Abs. difference: **1.0e-3** Negative eigenvalues: {**1**,**0**}

Abs. difference: **1.0e-3** Negative eigenvalues: **2**



Abs. difference: **1.0e-3** Negative eigenvalues: **1**



Abs. difference: **1.0e-3** Negative eigenvalues: **0**

Trust Region

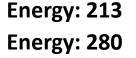
Guess 4, Widom 601bp

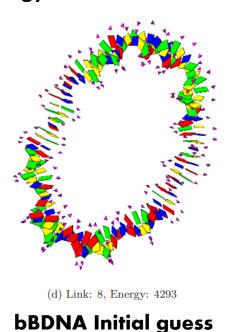
If we run Trust Region method we find two different solutions:

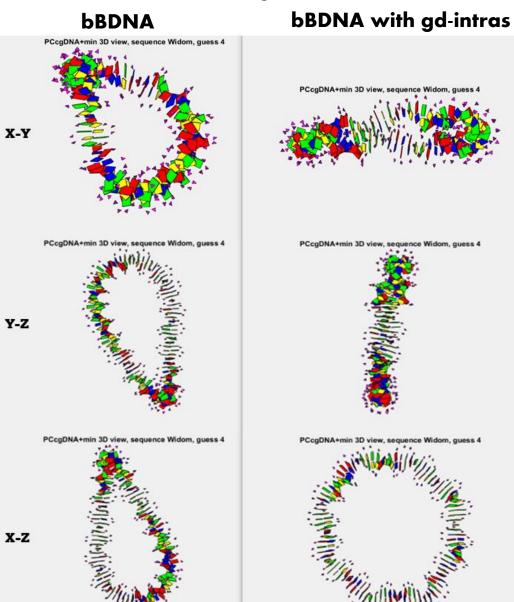
- one equal to M. Beaud one
- one closer to the initial guess

If we run Quasi-Newton + Trust Region method they both converge to the one Beaud found

Abs. difference: **1.0e-4** Negative eigenvalues: 0







Results

- > Pyne 339 (4 i.g.):
 - GUESS 1: they all converge to the same solution, and they are all local minima (Quasi-Newton + Trust Region)
 - GUESS 3: they all converge to the same solution, and they are all local minima
 - GUESS 6: they all converge to the same solution, and they are all local minima
 - GUESS 9: converge to the same point which is not a minimum



Abs. difference: **1.0e-4** Negative eigenvalues: **0**



Abs. difference: **1.0e-2** Negative eigenvalues: **0**



Abs. difference: **1.0e-2** Negative eigenvalues: **0**



Abs. difference: **1.0e-4** Negative eigenvalues: +**5**

Guess 9, Pyne 339bp

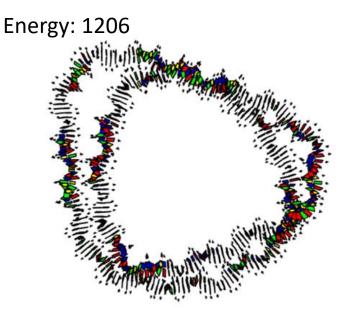
- Trust Region method is really slow
- *fminunc* stops because step-size is too short

Might be that in the starting point the function is too different from a quadratic so the algorithm need a really small region for the model to be adequate

Using Quasi-Newton we obtain a configuration closer to the initial guess but with much lower energy

bB En

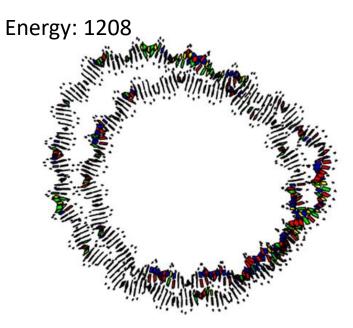
M. Beaud solution



bBDNA Initial guess

Energy: 65140

Quasi-Newton solution



Conclusions

> Minimum eigenvalue of the Hessian always really small (1.0e-08 ~ 1.0e-04)

> Maximum eigenvalue of the Hessian always really big (~1.0e+4)

Condition number of the Hessian really big (1.0e+09 ~ 1.0e+14)

This leads to oscillations and might be the reason why the convergence to the exact solution is really slow

The solutions with many negative eigenvalues also have gradients that are not close to the zero value

All energy optimization converge to the same configuration with the two different initial points



Thank you for listening!

DO YOU HAVE ANY QUESTION?